

GibbsCAM Post Department 2545 W Hillcrest Drive, Suite 210 Thousand Oaks, CA 91320 USA +1.800.654.9399 www.gibbscam.com

New Post Checklist

Dear Customer,

The Post Department at GibbsCAM wants to ensure that the first delivery of your post is as close to how you program your machine as possible, within the programming requirements of the GibbsCAM software. We do not want to force you to conform to our G-code format. *Instead, we feel that your familiarity with your code along with your local machine representative's guidance should inform us on how to output your code.*

In order to do that, we need information from you: how you program your machine, what requirements you have, how your machine was setup, etc. Please help us **provide you** with a post that outputs code you recognize by **providing us** with the following information:

Post Research Document filled out for this machine

Sample Program(s) that shows all the options you want your post to support

Machine Specs for this machine

Machine Schematics including Working Area and Reference Positions for each axis

Programming Manual from the Machine Tool Builder for this machine

With this information, we will build a post processor for you that will run your machine and that your programmer and operator will recognize immediately. When we build the post for you, here's **our commitment**: that with the format in your sample G-code, and the information found in the programming manual, we will deliver a working post, and fix any errors or format deviations for free.

In order to provide you that guarantee, we also need a *commitment* from you: that the information you provide is factual and complete; that it represents everything you need to run your machine.

After we deliver the post to you, any changes that may be requested will have to be evaluated against the original information provided. If the change deviates from the original information, then *a fee may be imposed in order for us to change the post*.

Agreed to by

Commited to by

The Gibbscam Post Department Team

Customer Contact Name

GibbsCAM Post Department

We look forward to working with you on this post processor project. If you have any questions or concerns, please contact us at <u>post@gibbscam.com</u>.



Post Processor Research for Milling

Please fill out all pages that pertain to your post processor so that your post is accurate. If it is available, any schematics and other machine documentation can be very helpful and may be all that is required.

GENERAL INFORMATION: Required

- 1. Customer Info
- 2. Post Info
- 3. Machine Specs

POST OPTIONS: Only fill out options you need.

- 4. Rotary Table
- 5. Rotary Head
- 6. Additional Linear Axes
- 7. Right Angle Head and Swivel Head





GENERAL CUSTOMER INFO

Company Name:	Location:
Contact Person:	Contact Phone:
Email Address:	Date:

GENERAL MACHINE INFO

Machine Make and Model:	
Machine Build Year:	Serial#:
Control Make and Model:	Software Version:
Does your machine have rotary axes?	
NO	
A-axis (rotates around X-axis) B-axis (ro	tates around Y-axis) C-axis (rotates around Z-axis)
Rotating Head Rotating	Table
Does your machine support additional linear axes?	Does your machine support swapping heads?
YES NO	YES NO
Machine Orientation: Vertical Mill	Horizontal Mill

GIBBSCAM OPTIONS

What GibbsCAM version will you use with this machine?	
What GibbsCAM options should the new Post Processor sup Tombstone Management System	port? Broaching
5-Axis Simultaneous Cutting	GibbsCAM Probing
Eccentric/Elliptical Turning	Head Changing (swappable heads)





UTILITY OPERATIONS

Will you need the ability to program any Utility Operations, such as Tailstocks or Quills? If so, please enter the names of the Utility Operations you will need, separated by commas.

EXISTING POST AS EXAMPLE

Do you have an existing GibbsCAM post that should serve as an example of how you want the new post to output? If so, please enter the name of the Post below.

(NOTE: All new GibbsCAM posts are made from the latest template. We will not modify an existing post. Instead, we will make sure that the new post outputs in a similar way to the existing post.

OUTPUT OPTIONS

Which Output Modes will your post need to support? (Post Department may need to contact you for additional information.) (Check all that apply)

Multiple WFOs (G54-G59, G505-G599.Cycle 247) Workplanes (G68.2, Cycle 800, Plane Spatial) Dynamic Work Fixtures (G54.2, CALL 0088, G254) TCP (G43.4, TRAORI, M128) 3D CRC (Tool Tip) Adjustment

SUB PROGRAM MANAGEMENT

Sub Program: How does the post call a Sub Program? Sub Program: Sub Routine: No Subs: Sub Location must be: Below the main program in the same file In a separate file By default we increase the Number from the Main program: Use the default (increase Subs by 1 from the Main program) Start numbering from:





Machine Specs

MACHINE SPECS

Distance from the ce	enter of table	in each dire	ction [mm.]:	
X-axis:	:		Z-axis:	
Linear axes: Specify	what moves v	when the axi	is is moved?	
X-Axis:	Tool	Part		4
Y-Axis:	Tool	Part		
Z-Axis:	Tool	Part		\leq
Minimum and Maxin	num travel dis	stance for e	ach axis [mm.]:	
X-axis:	Minimum		Maximum	
Y-axis:	Minimum		Maximum	
Z-axis:	Minimum		Maximum	, i

MILLING SPINDLE

Speed [in R	PMs]:	Minimum	Maximum				
Tool holder	Tool holder type and size [HSK, CAT40]:						
Number of tool positions:				Tool changing time [Seconds from tool to tool]:			
Maximum o	utting fe	edrate [mm./minute]:	:				
X-ax	is:	Minimum	Maximum				
Y-ax	is:	Minimum	Maximum				
Z-ax	is:	Minimum	Maximum				
Rapid feedr	ate [mm	./minute]:					
X-ax	is:	Minimum	Maximum				
Y-ax	is:	Minimum	Maximum				
Z-ax	is:	Minimum	Maximum				

COOLANT OPTIONS

Name	On	Off
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		

Example

Name	On	Off
1 Flood	M8	M9
2 Thru Spindle	M7	M9
3 Pulse	M25	M28



4 Rotary Table

YES, this post needs to support a Rotary Table. If NO, please skip this page.

NOTE: If you provide Schematics for your Rotary Table or Indexer, please skip the rest of this page.

Some machines orient the rotating axes by either the part or the tool. Some machines have these rotary axes on the table, or on the tool, or on both simultaneously. Your Post Developer needs additional information on which linear axes the rotary axes rotates around, the distance from the table to the center of rotation, and the direction of the positive direction.

1. My Rotary Axes ro	otate along the (cho	ose	all that appl	y):	
A-axis (re	otates around X-ax	is)			
B-axis (re	otates around Y-axi	is)			
C-axis (re	otates around Z-axi	s)			
2. Type of Rotary Tal	ble (Choose a, b, or	c):			
2a. Integrated S	5-axis rotary axes		2b: Bolt	on 4-axis table	2c: Bolt on 5-axis table
L1: Distance	from top of table i	to	L1: I	Distance from top of table to	L1: Distance from top of table
center o	f rotation:		(tenter of rotation:	to center of rotation:
			L2: [Distance:from center of table	L2: Distance from center of table
			t	o location of 4th axis:	to location of 5th axis:
			L	.2 (in mm.):	L2 (in mm.):
3. When looking from	m the positive side	towa	rd the nega	itive direction, a positive angle r	otates which direction?
A-axis:	Clockwise		Count	erclockwise	
B-axis:	Clockwise		Counterclockwise		
C-axis:	Clockwise		Counterclockwise		
4. Many machines h Enter this limit for	ave limits on the ro r each axis (e.g. A90	otary)° to .	axes. A-90°). If the	e axis of rotation has NO limit, le	eave this field empty.
A-axis:	Min.	o	to Max.	o	
B-axis:	Min.	o	to Max.	0	
C-axis:	Min.	o	to Max. °		
5. What is the Maximum Rapid Rate and Cutting Feedrate for your rotary axes [°/minute]?					
A-axis:	Max. Rapid Rate		o	Max. Cutting Feedrate	0
B-axis:	Max. Rapid Rate		° Max. Cutting Feedrate °		o
C-axis:	Max. Rapid Rate		° Max. Cutting Feedrate °		
6. Do you use M <codes> to clamp the rotary axes?</codes>					
NO, I do	not have or do not	wan	t to use rota	ary clamping codes.	
YES. Please using the following Clamping Codes for my machine:					
A-axi	s: On:		Off:		
B-axi	s: On:	On: Off:			
C-axi	s: On:		Off:		



5 Rotary Head

YES, this post needs to support a Rotary Head. If NO, please skip this page.

NOTE: If you provide separate Schematics for your Rotary Head or Indexer, then please skip the rest of this page.

Rotary axes assigned to linear axes:

- A (rotates around the linear axis X)
- B (rotates around the linear axis Y)
- C (rotates around the linear axis Z)

ROTARY AXES ON HEAD

Choose one of the machine heads below and enter the measurement indicated:





6 Additional Linear Axes

YES, this post needs to support Additional Linear Axes. If NO, please skip this page.

Typical machines support up to 5 axes (XYZ ABC), but some support additional axes, like a W axis for a Quill, or a U-axis for a Head. Here are some examples:					
V-axis V-axis B		-Z-axis W-axis	V-axis Z-axis		
1. What additional axes does your machine su	pport?				
Label:	Linear	Rotary			
Label:	Linear	Rotary			
Label:	Linear	Rotary			
NO, it is only used for Positioning c YES, my machine can cut while inte	or Parking the axis. Proolating this axis.				
3. What is the maximum cutting feedrate and	maximum rapid rat	e for your additio	nal axes [°/minute]?		
Label:	Cutting Feedra	te:	Rapid Rate:		
Label:	Cutting Feedra	te:	Rapid Rate:		
Label:	Cutting Feedrate: Rapid Rate:				
4. What is the distance of any additional axis/a	ixes from the Home	position to the ta	able?		
Label:	Label: Distance to table [in mm.]:				
Label:	Distance to table [in mm.]:				
Label:	Distance to table [in mm.]:				
5. What is the Minimum and Maximum travel distance of your additional axes [mm.]?					
Label:	Minimum	Max	imum		
Label:	Minimum Maximum				
Label:	Minimum	Max	imum		



7 Right Angle Head and Swivel Head

YES, this post needs to support a Right Angle Head. If NO please skip this page.

REQUIRED: Please include schematics of the Right Angle Head REQUIRED: Please provide sample g-code of Right Angle Head in cutting operations REQUIRED: Please answer all questions below for an accurate display in GibbsCAM

